

# Randomized Quasi-Newton Updates are Linearly Convergent Matrix Inversion Algorithms

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Joint work with Peter Richtárik



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# Inverting a Matrix

# The Problem

The diagram illustrates the matrix equation  $AX = I$ . The matrix  $A$  is annotated with a vertical blue bracket on its left side labeled  $n$ . The matrix  $X$  is annotated with a horizontal blue bracket above it labeled  $n$ . A yellow callout box containing the text  $\in \mathbb{R}^{n \times n}$  has a yellow arrow pointing to the matrix  $X$ . Another yellow callout box containing the text "Identity matrix" has a yellow arrow pointing to the matrix  $I$ . The equation is written as  $AX = I$  with two horizontal lines under the equals sign.

$$AX = I$$

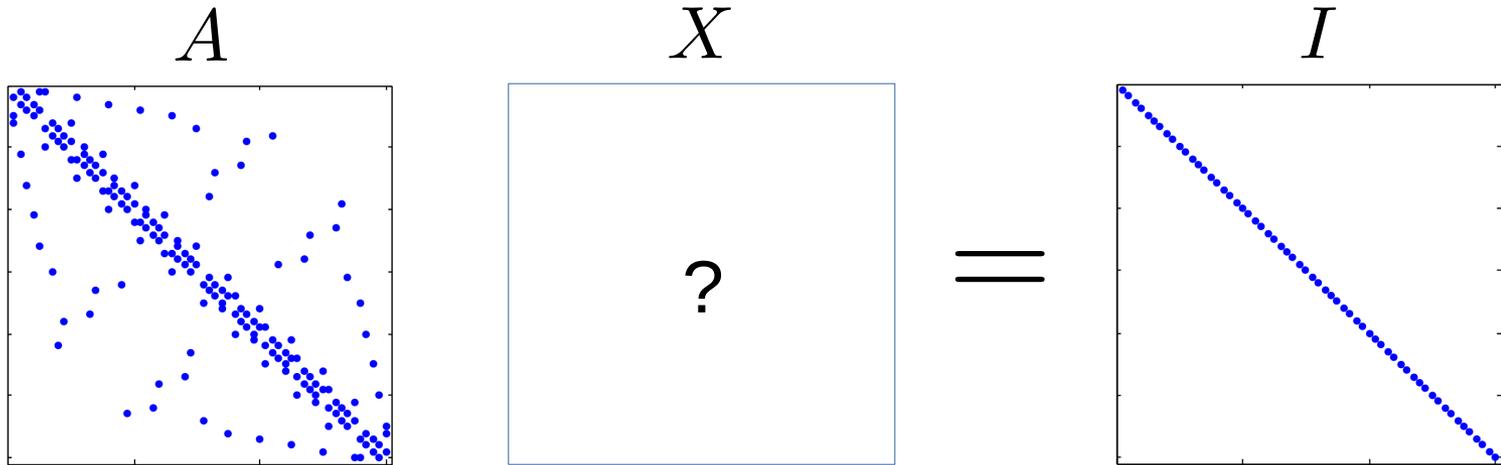
**Assumption:** The matrix  $A$  is nonsingular

# Why iteratively invert a matrix?

- Matrix inverse standard tool (needed to calculate a Schur complement or a projection operator)
- Starting point for **randomized variable metric**
- Starting point for **randomized preconditioning**

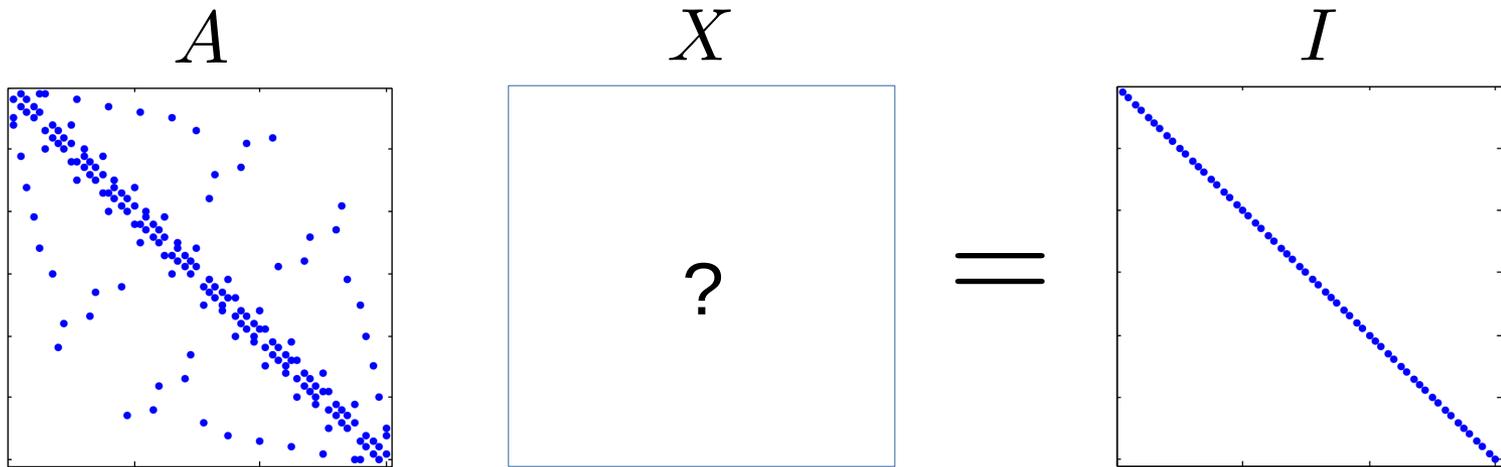
# Randomized Methods for Nonsymmetric Matrices

# The Sketching Idea



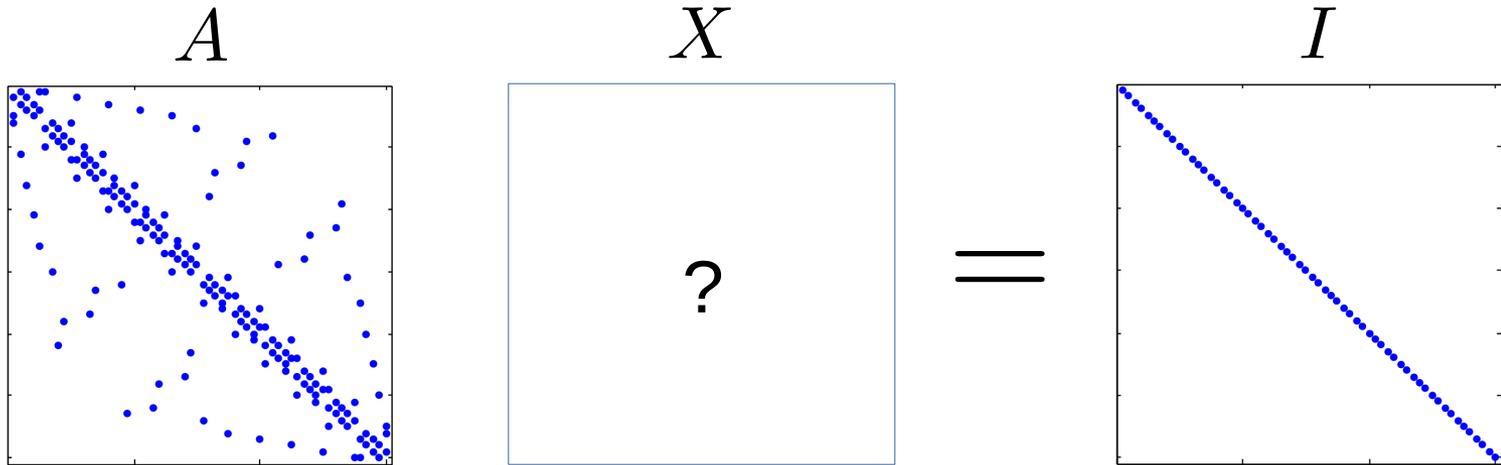
Compress system with random thin **random** matrix  $S \in \mathbf{R}^{n \times \tau}, \tau \ll n$ .

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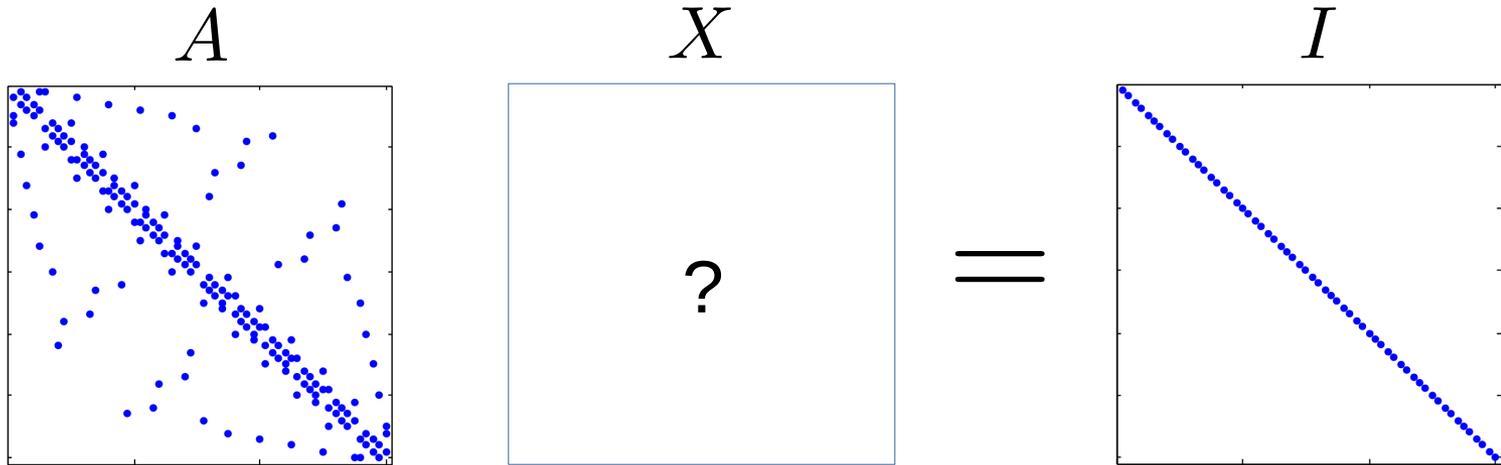
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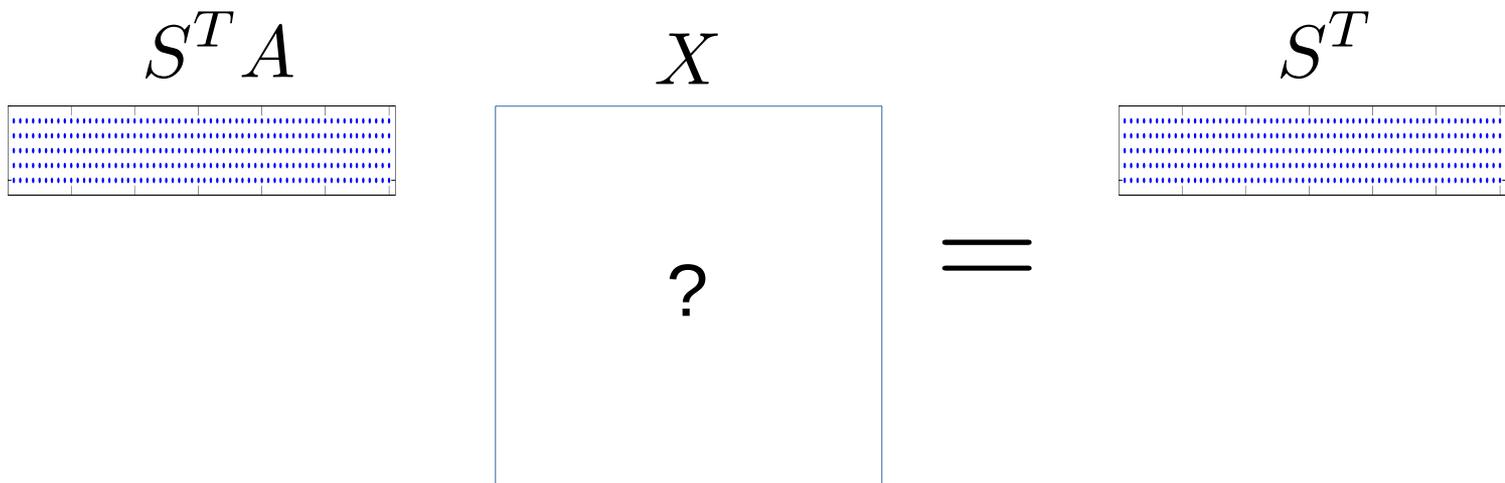


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# The quasi-Newton Viewpoint: “Sketch and Project”

$$X_{k+1} = \arg \min_{X \in \mathbb{R}^{n \times n}} \|X - X_k\|_{F(W^{-1})}^2$$

subject to  $S^T A X = S^T$

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$W$  : Symmetric and positive definite

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Includes methods good/bad Broyden, simultaneous Kaczmarz ...etc

# Randomized Methods for Symmetric Matrices

$$A = A^T$$

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**Connection to quasi-Newton Methods:** randomized block extension of the quasi-Newton updates.

$$S = \delta \in \mathbb{R}^n \quad \text{and} \quad \gamma := A\delta$$

and  $A$  is a “Hessian” we would like to invert. To be cheap, we can only sample the action  $A\delta$

$$\text{secant equation: } XAS = S \quad \longrightarrow \quad X\gamma = \delta$$



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$$\int_0^1 \nabla^2 f(x_k + t\delta) \delta dt$$

**quasi-Newton Methods:** randomized  
quasi-Newton updates.

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## 2. The Approx. Preconditioning viewpoint: “Constrain and Approximate”

$$X_{k+1} = \arg \min_{X \in \mathbb{R}^{n \times n}} \|X - A^{-1}\|_{F(W^{-1})}^2$$

subject to  $X = X_k + Y S^T A W + W A^T S Y^T$

$$Y \in \mathbb{R}^{n \times \tau} \text{ is free}$$

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**Duality:** This is a dual problem of the sketch and project viewpoint, new insight into quasi-Newton methods.

# New viewpoint for BFGS

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**Duality:** The BFGS projects the inverse onto a 2-dimensional space of symmetric matrices

### 3. Algebraic Viewpoint “Random Update”

$$H := S(S^T A W A^T S)^\dagger S^T$$

$$X_{k+1} = X_k - (X_k A - I) H A W \\ + W A H (A X_k - I) (A H A W - I)$$

# 3. Algebraic Viewpoint “Random Update”

Moore-Penrose  
pseudo inverse

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**Low rank  $3 \times \tau$  update**

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# 4. Analytic Viewpoint “Random Fixed Point”

$$R_k := X_k - A^{-1}$$

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A positive Linear operator  
applied to old residual  
defines the new residual

# Complexity / Convergence

## Theorem [GR'16]

If  $S$  has full column rank with probability one then

$$1 \quad \|\mathbf{E}[X_k - A^{-1}]\|_{W^{-1}} \leq \rho^k \|X_0 - A^{-1}\|_{W^{-1}}$$

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and if  $\mathbf{E}[H] \succ 0$  then

$$2 \quad \mathbf{E}[\|X_k - A^{-1}\|_{F(W^{-1})}^2] \leq \rho^k \|X_0 - A^{-1}\|_{F(W^{-1})}^2$$

# Case study of $\mathbf{E}[H]$

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## Special Choice of Parameters

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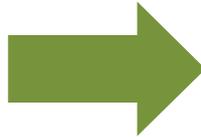
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$$\begin{aligned}\mathbf{E}[H] &= \frac{1}{m} \sum_{i=1}^m \frac{e_i e_i^T}{\|A_{i:}\|_2^2} \\ &= \text{diag}(\|A_{i:}\|_2^2)\end{aligned}$$

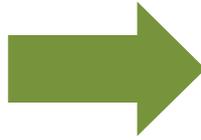
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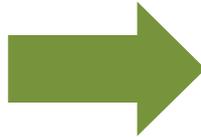
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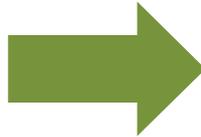
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Positive definite when  
A has no zero rows

# The rate: lower and upper bounds

## **Theorem [RG'15]**

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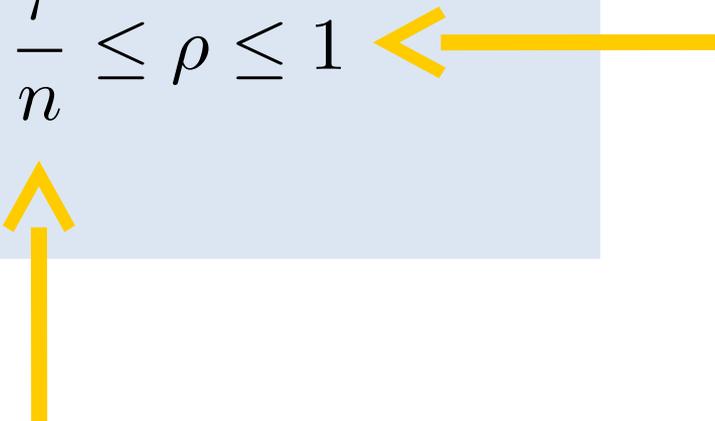
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**Insight:** The lower bound on the rate is better for  $S$  high rank, that is, when the dimension of the search space in the “constrain and approximate” viewpoint grows.

# Special Case: Randomized Block BFGS

# Randomized BFGS

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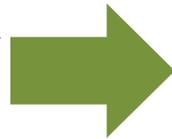
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**Complexity Rate.**  $A$  is positive definite  $\Rightarrow \mathbf{E}[H] \succ 0$

$$p_i = \frac{A_{ii}}{\mathbf{Tr}(A)}$$

$$\mathbf{E}[\|AX_k - I\|_F^2] \leq \left(1 - \frac{\lambda_{\min}(A)}{\mathbf{Tr}(A)}\right)^k \|AX_0 - I\|_F^2$$

# Convenient probability

## Theorem [GR'15]

$\bar{S} := [S_1, \dots, S_r]$  is nonsingular

$$\mathbf{P}(S = S_i) = p_i = \frac{\mathbf{Tr}(S_i^T A W A^T S_i)}{\mathbf{Tr}(\bar{S}^T A W A^T \bar{S})}$$

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$$\rho = 1 - \frac{1}{\kappa^2(W^{1/2} A^T \bar{S})}$$

$$\kappa(W^{1/2} A^T \bar{S}) := \|(W^{1/2} A^T \bar{S})^{-1}\|_2 \|W^{1/2} A^T \bar{S}\|_F \geq \sqrt{n}$$

# Randomized Block BFGS

$$X_{k+1} = \arg \min_{X \in \mathbb{R}^{n \times n}} \|X - X_k\|_{F(A)}^2$$

subject to  $S^T A X = S^T, \quad X = X^T$

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**Complexity Rate.** If  $A$  is positive definite  $\Rightarrow \mathbf{E}[H]$  is nonsingular

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**Idea:** To minimize condition number, choose  $S$  so that  $\bar{S}$  is an approximate inverse of  $A^{1/2}$

$$p_i = \frac{\text{Tr}(S_i^T A S_i)}{\text{Tr}(\bar{S}^T A \bar{S})}$$

$$\mathbf{E}[\|AX_k - I\|_F^2] \leq \left(1 - \frac{1}{\kappa^2(A^{1/2}\bar{S})}\right)^k \|AX_0 - I\|_F^2$$

# Adaptive Randomized Block BFGS (adaRBFGS)

$$\mathbf{E}[\|AX_k - I\|_F] \leq \left(1 - \frac{1}{\kappa^2(A^{1/2}\bar{S})}\right)^k \|AX_0 - I\|_F$$

To minimize condition number:

$$\text{If } \bar{S} = A^{-1/2} \text{ then } \kappa(A^{1/2}\bar{S}) = \kappa(I) = \sqrt{n}$$

$$X_k \rightarrow A^{-1} \quad \longrightarrow \quad X_k^{1/2} \rightarrow A^{-1/2}$$

$$i\bar{S} = X_k^{1/2}?$$

# Adaptive Randomized Block BFGS (adaRBFGS)

Maintain and update  $L_k = X_k^{1/2}$

adaRBFGS\_cols:

$$S = L_k I_{:C}, \quad C \subset \{1, \dots, n\} \text{ random set}$$



$$\bar{S} = L_k = X_k^{1/2}$$

adaRBFGS\_guass:  $S \sim \mathcal{N}(0, X_k)$

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Gratton, S., Sartenaer, A., & Illunga, J. T. (2011). **On a Class of Limited Memory Preconditioners for Large-Scale Nonlinear Least-Squares Problems**. SIAM Journal on Optimization, 21(3), 912-935.

# Experiments

# Current state of the art

## Symmetric Newton-Schulz

$$X_{k+1} = 2X_k - X_k A X_k$$

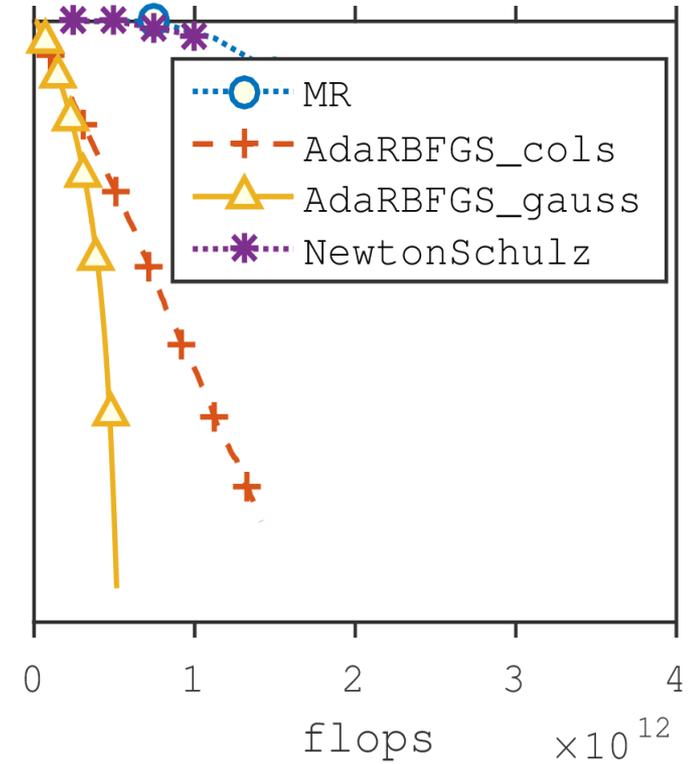
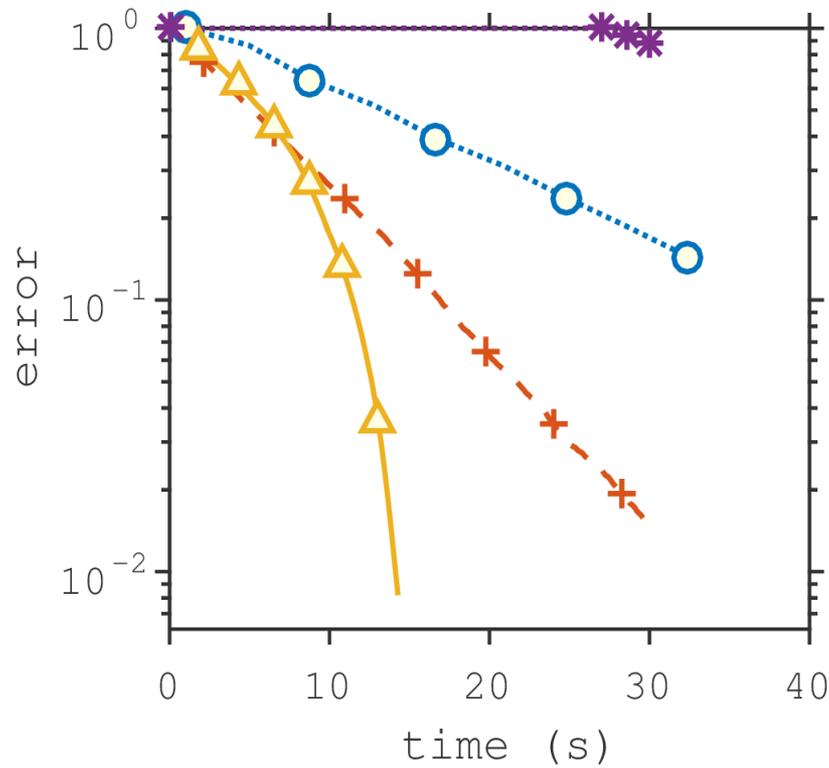
## Self-conditioning Minimal Residual (MR)

$$X_{k+1} = \arg_X \min \|AX - I\|_F^2$$

subject to  $X = X_k + \alpha X_k (AX_k - I)$

# Synthetic Problem

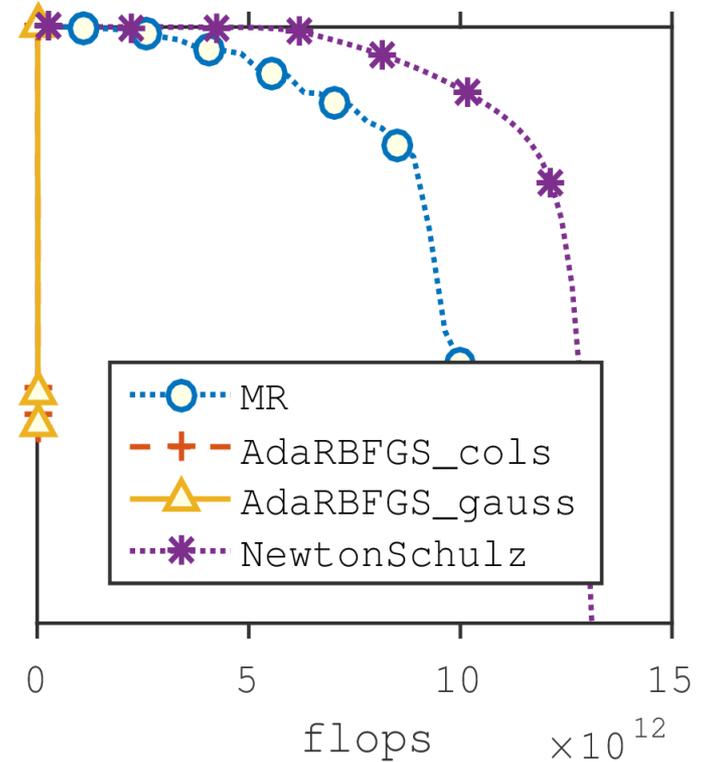
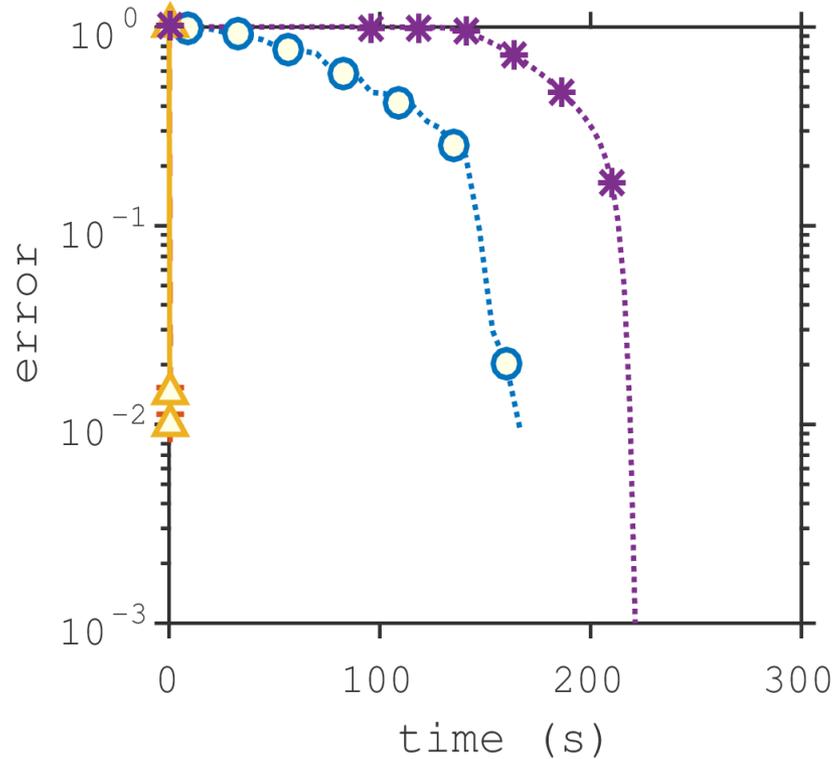
Synthetic data



(randn,  $n = 5000$ )

# Ridge Regression Hessian

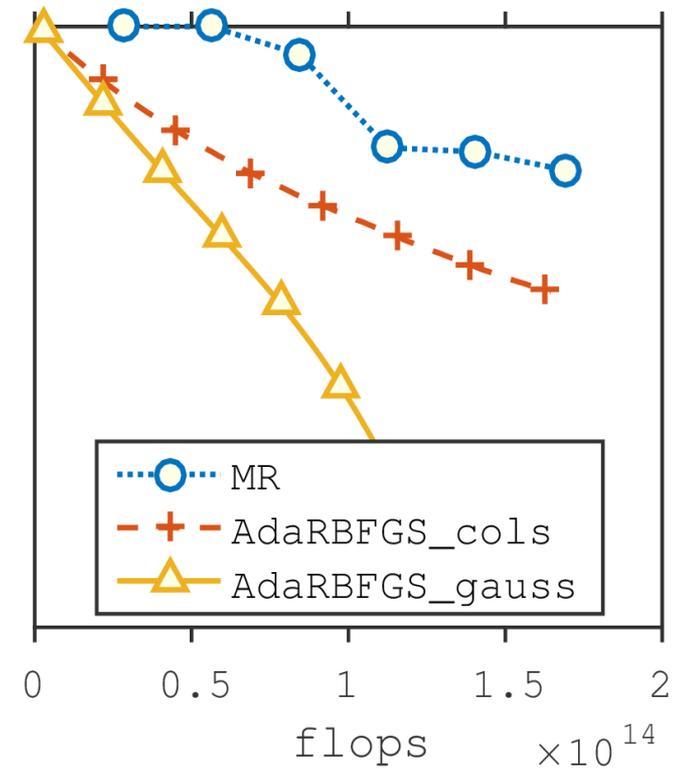
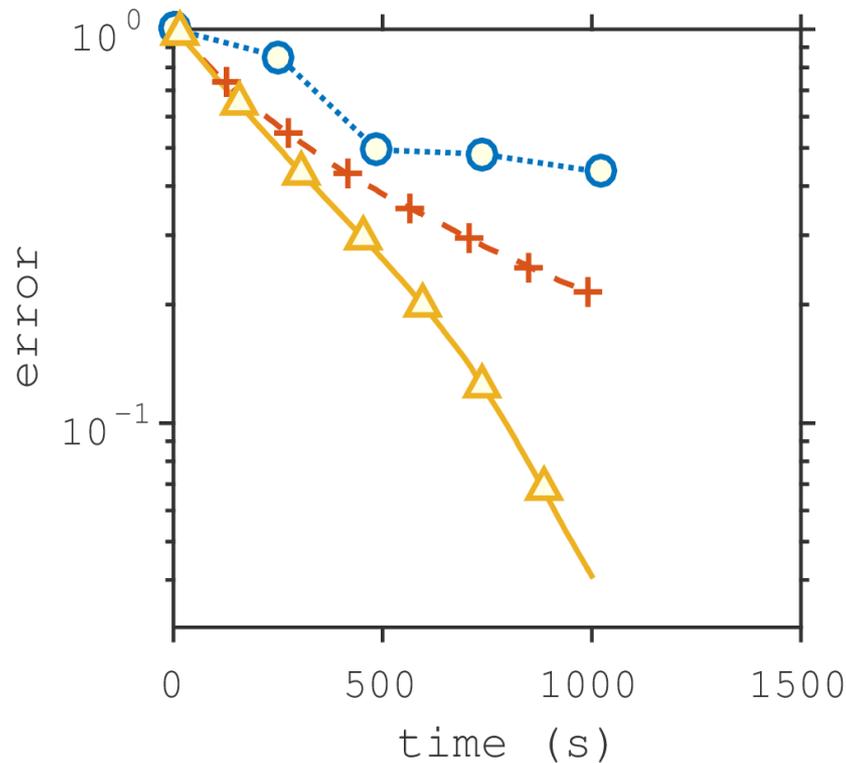
LIBSVM data



(gisette,  $n = 5,000$ )

# Sparse Matrices from Engineering

UF collection



(GHS psdef/wathen100,  $n = 30,401$ )

# Conclusion

- **New randomized methods** for calculating of approximate inverses of large-scale matrices
- **Convergence rates** which can form the basis of convergence of preconditioning or variable metric methods.
- **Dual viewpoints** of classic quasi-Newton methods, connection to Approximate Inverse Preconditioning methods
- **Can be extended** to calculating pseudo-inverse

Thank you,  
Questions?



RMG and Peter Richtárik

## **Randomized Iterative Methods for Linear Systems**

SIAM. J. Matrix Anal. & Appl., 36(4), 1660–1690, 2015



RMG, D. Goldfarb and Peter Richtárik

## **Stochastic Block BFGS: Squeezing More Curvature out of Data**

ICML, 2016



RMG and Peter Richtárik

## **Randomized Quasi-Newton Updates are Linearly Convergent Matrix Inversion Algorithms**

Preprint arXiv:1602.01768, 2016